ROBOTIC PALLETIZING EXPERTS


## OPERATIONAL SPECIFICATIONS

Motion- Multi-articulated, polar coordinate system Load Capacity - $310 \mathrm{lbs} . / 140 \mathrm{~kg}$. (including end effector)

- 440 lbs./200 kg. (optional)

Degree of Freedom- 4 axis
Operating Range-
$R$ axis (rotation)
D axis (up/down)
O axis (forward/back)
T axis (wrist)
Maximum Speed/Minute- for a 'single pick'
Note:'Multi-picking' product will increase palletizing rates. Product size and pattern may affect palletizing rates.
Accuracy- Repeated stop position accuracy $\pm 1 \mathrm{~mm}$

## ROBOTIC ARM MECHANICAL \&

 ㅌㅌTRICAL SPECIFICATIONS
## Electrical-

$200 / 220 \mathrm{~V} \pm 10 \%, 60 \mathrm{~Hz}, 3 \mathrm{Ph}, 7$ Amps
$200 / 220 \mathrm{~V} \pm 10 \%, 60 \mathrm{~Hz}$, $3 \mathrm{Ph}, 18 \mathrm{Amps}$
$460 \mathrm{~V} \pm 10 \%, 60 \mathrm{~Hz}, 3 \mathrm{Ph}, 3.5 \mathrm{Amps}$ (optional)
$460 \mathrm{~V} \pm 10 \%, 60 \mathrm{~Hz}, 3 \mathrm{Ph}, 9$ Amps (optional)
Note: Peripheral system components
will require additional power consumption
Pneumatic Consumption-
6.36 SCFM/180 liter/min (ANR)

Note: Pneumatic consumption may vary with system options
Robot Weight- Without end effector \& control panel
Catagory 3 Circuit

| A $1 / 20$ | $A 1600$ | $A / 1: 00$ |
| :---: | :---: | :---: |
| X | X | X |
| X | X | X |
|  | X |  |
| X | X | X |
| $360^{\circ}$ | $360^{\circ}$ | $360^{\circ}$ |
| $91^{\prime \prime} / 2300 \mathrm{~mm}$ | 91"/2300mm | 91"/2300mm |
| $69^{\prime \prime} / 1750 \mathrm{~mm}$ | $60^{\prime \prime} / 1518 \mathrm{~mm}$ | $60^{\prime \prime} 11518 \mathrm{~mm}$ |
| $440^{\circ}$ | $440^{\circ}$ | $440^{\circ}$ |
| $9 \mathrm{cases} / 11 \mathrm{bags}$ | 18cases/24bags | 20cases/28bags |
| X | X | X |
| X |  |  |
|  | X | X |
| $\chi$ | X | X |
| X | X | X |
| 2756lbs/1250kg | 2560lbs/11 60 kg | 2645lbs/1200kg |

Includes 2 channel e-stop, redundant 3-phase contactors, trapped key door interlock system and light curtains, all monitored by safety relay
Certified to UL1740 Standards by a NRTL (Nationally Recognized Test Laboratory)
UL1740 is the standard for Safety for Robots and Robotic Equipment
UL 1740 encompasses applicable requirements of the following standards:
ANSI RIA 15.06-1999 Industrial Robots and Robot Systems- Safety Requirements
CSA 2434-03 Industrial Robots and Robot Systems- General Safety Requirements
NFPA 792008 National Fire Protection Association Electrical Standards for Industrial Machinery
NEC 2008 [NFPA 70) National Electrical Code
UL508A Standard for Safety for Industrial Contol Panels
In addition, Columbia/Okura is a UL508A controls manufacturing facility
UL508A: UL File \# E216389 (U.S.- NITW.E216389, Canada- NITW.E216389)
Standard for Safety for Industrial Control Panels (U.S. \& Canada)
Specifications are subject to change without notice


Dimensions in inches


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PIMIMI
USA

## INSIST ON PALLETIZERS THAT FIT

Whether you're buying your 1st or your 51st palletizer, don't waste your time on inflexible equipment. Insist on a palletizer that fits into your floor layout, your work flow, your products and your future production plans.

## Roboshield Collision Detect Function



Columbia/Okura, LLC headquarters, Vancouver, WA USA

## EXPERIENCE YOU CAN COUNT ON

Columbia/Okura is a manufacturer and technical integrator of robotic palletizing systems to handle cases, bags, pails, bundles, bales, trays, pallets and sheets, reducing overall labor costs and increasing profitability to manufacturers throughout the world. Columbia/Okura is jointly owned by Columbia Machine, an industry leader in conventional palletizing and Okura Yusoki, Japan's leading supplier of robotic palletizing systems. We put over 100 years of combined material handling experience and over 40 years of combined robotic palletizing expertise into every machine produced.

Columbia/Okura's Roboshield feature reduces the risk of damage to the robot in the event of a collision. State-of-the-art software automatically triggers an emergency stop if the end effector or arm collides with peripheral equipment or stacked load.

Note: System safety guarding has been removed for image clarity.



Single Line Layout

d a wide range of standard end effectors to handle virtually any product, including cases, bags, trays, totes, bales, bundles, crates, pails, p carries service parts for immediate support on all these standard designs. The end effectors shown here are some of the most common tyf

## FORK STYLE

Cases, trays, bundles, etc.

CASE/BAG


## VACUUM STYLE

Cases
allets and oes utilized.

## CONTROLS SOFTWARE AND PROGRAMMING

The Columbia/Okura robotic palletizing system utilizes highly advanced software to create pattern programs. The operating screen, complete with detailed graphics and easy navigation tools, provides quick access to the 50 standard product patterns already built into the program. OXPA-DIY "Do-it-Yourself" software is designed to make adding patterns to your robot a simple process. Custom patterns are created off-line on your personal computer or laptops, and then downloaded to the robot controller. Patterns can also be added at the control panel using the operator interface. No need to interrupt your production schedule; custom patterns can be created offline while your system is running, and downloaded between production runs.


## 2 SELECT PATTERN.



DIY displays
possible stacking
configurations based on your input. Just click on the one you want and the software automatically calculates the stacking coordinates for you.

